



# FAST OPTIMIZATION OF BOOLEAN QUADRATIC FUNCTIONS VIA ITERATIVE SUBMODULAR APPROXIMATION AND MAX-FLOW

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## Introduction:

- Optimization problem** – minimizing arbitrary quadratic forms over the  $\{0,1\}$  (Boolean) lattice

$$\min_{\mathbf{x} \in \{0,1\}^n} \left\{ f(\mathbf{x}) := \mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{b}^T \mathbf{x} \right\}$$

## Applications

- ML multi-user MIMO detection [Ma et al., 2002]
- Design of CDMA spreading codes [Karystinos-Liavas, 2010]
- Mode computation in  $\{0,1\}$  undirected MRFs [Kolmogorov-Zabih, 2004]
- Mining dense sub-graphs [Tsourakakis et al., 2013]

## Non-convex and NP-hard

- Our approach** – exploit combinatorial structure to construct and iteratively minimize a sequence of global submodular upper bounds on the cost function via the Max-Flow algorithm

## Prior Art:

- Semi-Definite Relaxation + randomized rounding** – [Luo et al., 2010]. Sub-optimality guarantees in special cases, high complexity
- Algorithm of [Karystinos-Liavas, 2010]**. Exact maximization of rank-deficient quadratic forms in polynomial-time, high complexity
- Maximum Flow** – [Kolmogorov-Zabih, 2004]. Exact minimization of quadratic **submodular** functions in polynomial-time

## Submodularity:

- Given a set of elements  $\mathcal{V} = [n] := \{1, \dots, n\}$ , consider a set-function  $f : 2^{\mathcal{V}} \rightarrow \mathbb{R}$
- Submodular** if for all  $\mathcal{A} \subseteq \mathcal{B} \subseteq \mathcal{V} \setminus \{e\}$ ,



$$F(\mathcal{A} \cup \{e\}) - F(\mathcal{A}) \geq F(\mathcal{B} \cup \{e\}) - F(\mathcal{B})$$

i.e., diminishing returns

- Exact minimization in polynomial-time [Grotschel et al., 1981].
- A quadratic set-function is submodular iff all its **off-diagonal elements are non-positive** [Bach, 2013].

## The Recipe:

- Subset-selection form:

$$\min_{\mathcal{S} \subseteq \mathcal{V}} \left\{ f(\mathcal{S}) := \mathbb{1}_{\mathcal{S}}^T \mathbf{A} \mathbb{1}_{\mathcal{S}} + \mathbf{b}^T \mathbb{1}_{\mathcal{S}} \right\}$$

- Express  $f(\mathcal{S})$  as a **difference of submodular functions**,  $\mathbf{A} = \mathbf{A}_1 - \mathbf{A}_2$ , where  $\mathbf{A}_1 = \min\{\mathbf{A}, \mathbf{0}\}$  and  $\mathbf{A}_2 = \min\{-\mathbf{A}, \mathbf{0}\}$
- Obtain representation

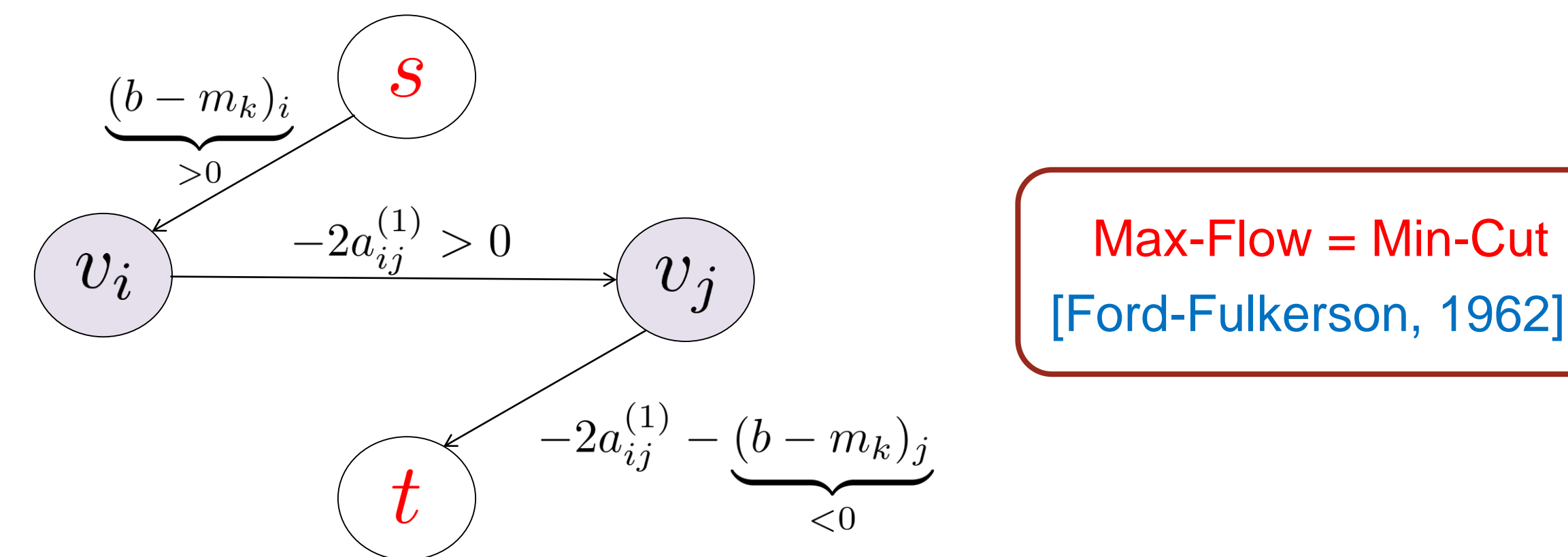
$$\min_{\mathcal{S} \subseteq \mathcal{V}} \left\{ f(\mathcal{S}) := \underbrace{\mathbb{1}_{\mathcal{S}}^T \mathbf{A}_1 \mathbb{1}_{\mathcal{S}} + \mathbf{b}^T \mathbb{1}_{\mathcal{S}}}_{g(\mathcal{S})} - \underbrace{\mathbb{1}_{\mathcal{S}}^T \mathbf{A}_2 \mathbb{1}_{\mathcal{S}}}_{h(\mathcal{S})} \right\}$$

- Majorize  $h(\mathcal{S})$  via modular function  $m_k(\mathcal{S}) := \mathbf{m}_k^T \mathbb{1}_{\mathcal{S}}$  satisfying
  - $h(\mathcal{S}) \geq m_k(\mathcal{S}), \forall \mathcal{S} \subseteq \mathcal{V}$ ,
  - $h(\mathcal{S}_k) = m_k(\mathcal{S}_k)$

- Obtain quadratic submodular minimization sub-problem

$$\min_{\mathcal{S} \subseteq \mathcal{V}} \left\{ \phi_k(\mathcal{S}) := \mathbb{1}_{\mathcal{S}}^T \mathbf{A}_1 \mathbb{1}_{\mathcal{S}} + (\mathbf{b} - \mathbf{m}_k)^T \mathbb{1}_{\mathcal{S}} \right\}$$

- Optimally solvable via Max-Flow [Kolmogorov-Zabih, 2004]



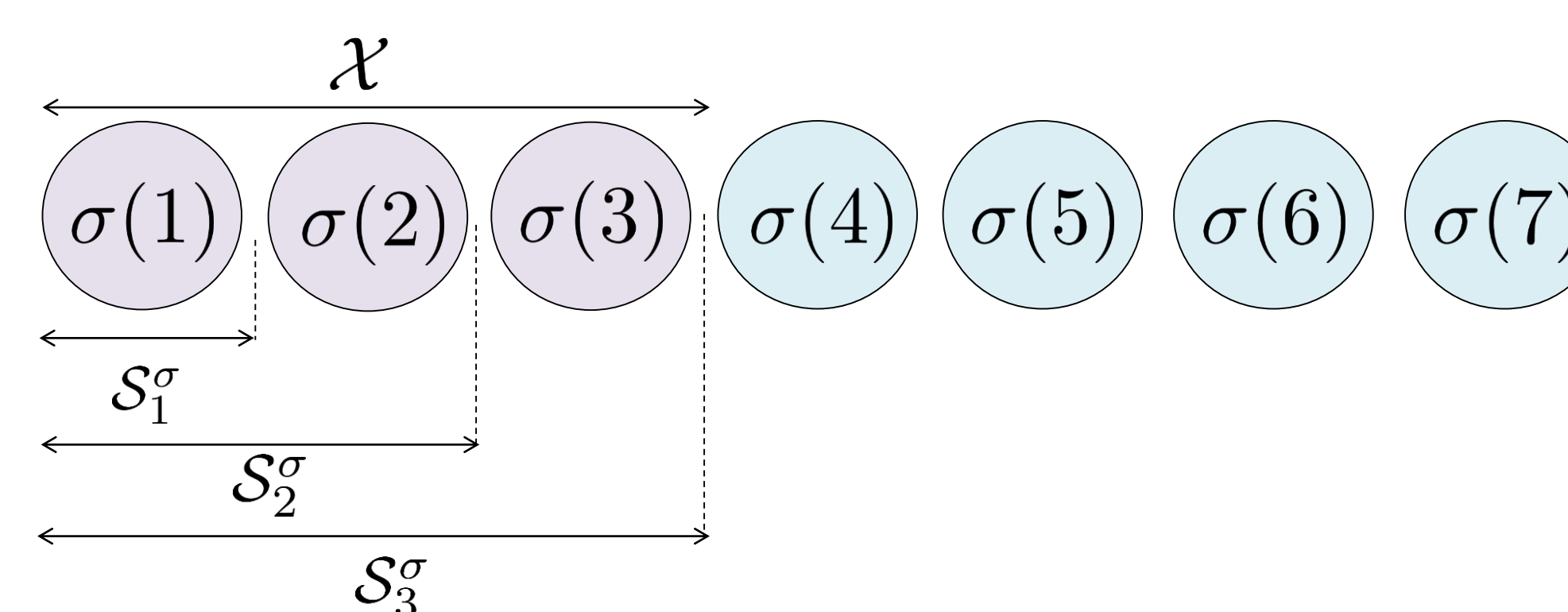
- Sequentially minimize series of global submodular upper bounds

## Construction of majorizer: [Narasimhan-Bilmes, 2005]

- Key fact:** **submodular functions possess sub-differential sets**, [Fujishige, 2004]

$$\partial h(\mathcal{X}) = \{ \mathbf{v} \in \mathbb{R}^n : h(\mathcal{Y}) \geq h(\mathcal{X}) + \mathbf{v}^T \mathbb{1}_{\mathcal{Y}} - \mathbf{v}^T \mathbb{1}_{\mathcal{X}}, \forall \mathcal{Y} \subseteq \mathcal{V} \}$$

- Compute sub-gradient of  $\partial h(\mathcal{X})$  using algorithm of [Edmonds, 1970]
- Generate permutation  $\sigma \in [n]$  with entries  $\sigma(i) \in \mathcal{X}, \forall i \leq |\mathcal{X}|$
- Generate nested subsets  $\mathcal{S}_0^\sigma = \emptyset, \mathcal{S}_i^\sigma = \{\sigma(1), \dots, \sigma(i)\}, \forall i \in [n]$



- Generate  $\mathbf{v}_{\mathcal{X}}^\sigma \in \mathbb{R}^n$  with entries  $v_{\mathcal{X}}^\sigma(\sigma(i)) = h(\mathcal{S}_i^\sigma) - h(\mathcal{S}_{i-1}^\sigma), \forall i \in [n]$

## The Algorithm:

- Initialize:**  $\mathcal{S}_0 \subseteq \mathcal{V}$  and generate permutation  $\sigma_0$  corresponding to  $\mathcal{S}_0$ , set  $k = 0$
- Repeat:**
- Compute sub-gradient  $\mathbf{v}_{\mathcal{S}_k}^{\sigma_k} \in \partial h(\mathcal{S}_k)$  via Edmond's procedure
- Use a Max-Flow algorithm to compute
 
$$\mathcal{S}_{k+1} \in \arg \min_{\mathcal{S} \subseteq \mathcal{V}} \{ \phi_k(\mathcal{S}) := \mathbb{1}_{\mathcal{S}}^T \mathbf{A}_1 \mathbb{1}_{\mathcal{S}} + (\mathbf{b} - \mathbf{v}_{\mathcal{S}_k}^{\sigma_k})^T \mathbb{1}_{\mathcal{S}} \}$$
- Form random permutation  $\sigma_{k+1}$  corresponding to  $\mathcal{S}_{k+1}$
- Set  $k = k + 1$
- Until:** termination criterion is met
- Properties:**
  - Successive approximation in  $\{0,1\}$  domain
  - Naturally respects  $\{0,1\}$  constraints
  - Monotonically reduces cost function

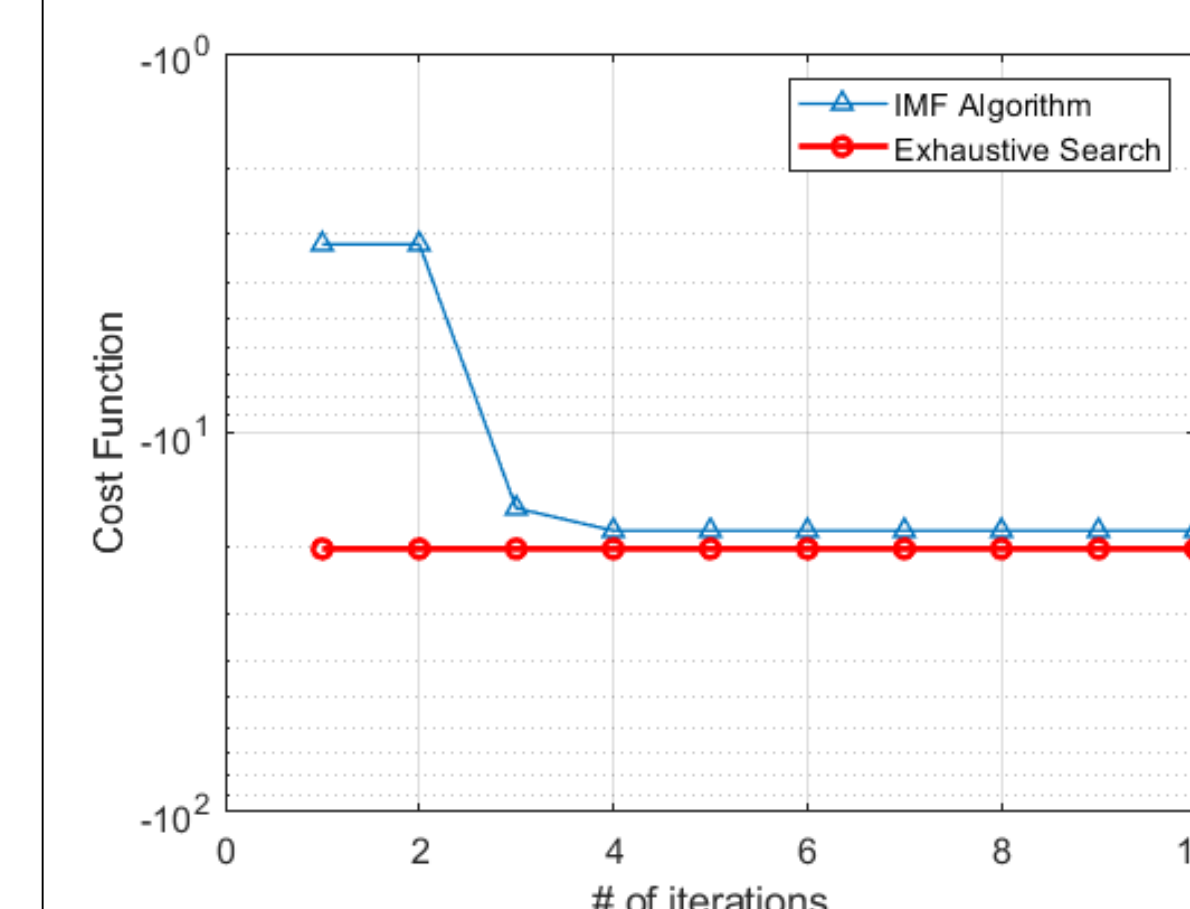
## Preliminary Results:

- Use Matlab's built in Max-Flow solver [Boykov-Kolmogorov, 2004]
- Mode computation in  $\{0,1\}$  undirected MRFs

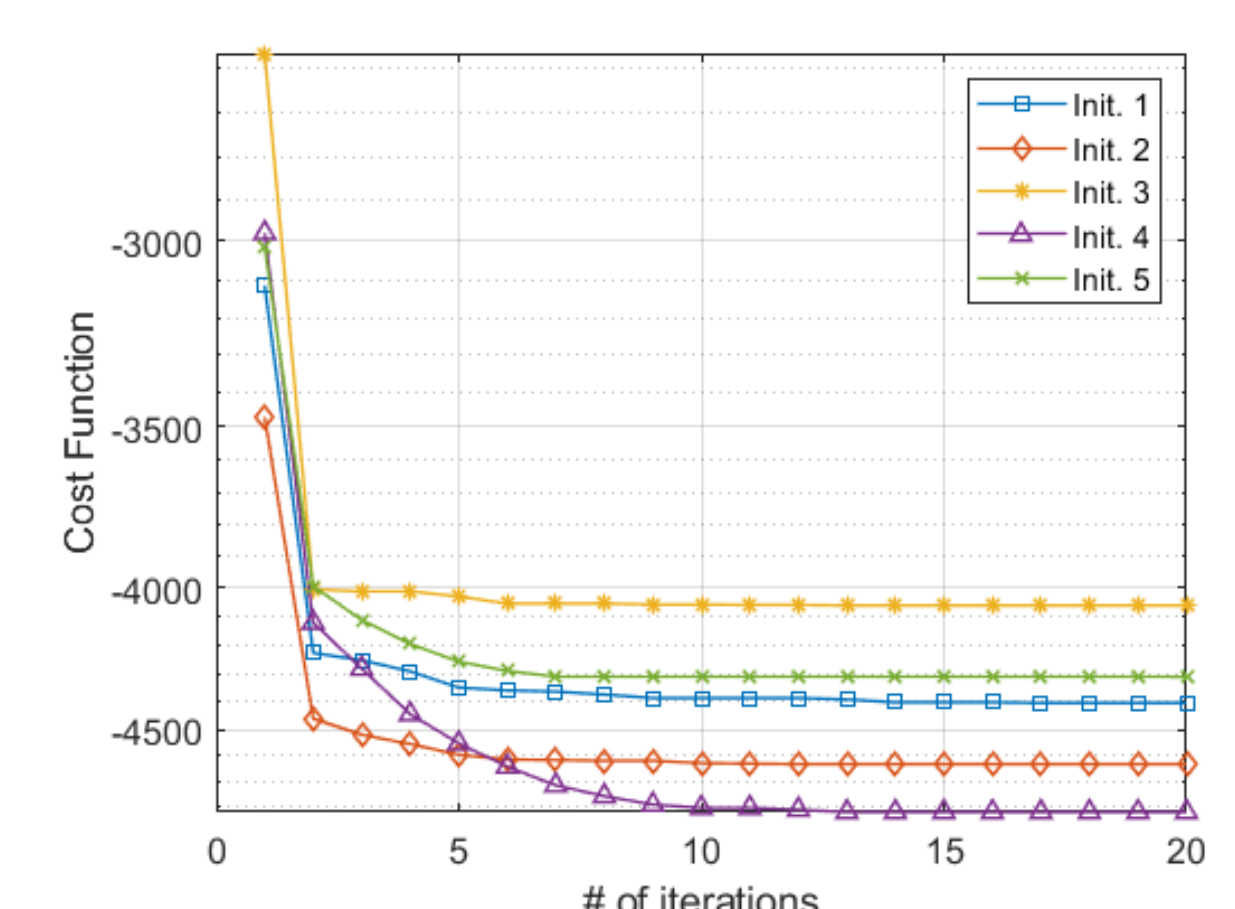
$$P(x_1, x_2, \dots, x_n) = \frac{1}{Z} \exp \left( - \sum_{i \in [n]} b_i x_i - \sum_{(i,j) \in \mathcal{E}} a_{ij} x_i x_j \right)$$

- Generate complete graph of pairwise-potentials, and randomly remove subset of edges

Figure: Evolution of cost function with iterations for  $n = 15$  and  $n = 1000$



Near-optimal for small instances at low complexity



Scalable to large instances, dependent on choice of initialization

## Conclusions:

- Approximate minimization of Boolean QP via iterative submodular approximation
- Future work – Tests on real world data, provide theoretical guarantees on performance.

